

1 **Automation in Museum Construction and Operation**

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6 **Abstract.** The conventional method in construction has many limitations and
7 therefore needs modification. Not only is this method inefficient, but it is also
8 harmful to the environment due to its high energy consumption. Therefore, there
9 is a rising need for automation in construction. This need is accentuated in
10 specific structures, such as museums, that are more creatively designed and have
11 more specific maintenance and operation requirements. The purpose of this paper
12 is to create a tool kit for automating the design, construction, and operation of
13 museums while considering sustainability measures. The main methodology is
14 research on the application of Building Information Modeling (BIM), robotics,
15 and 3D printing during the design and construction stages, and examination of
16 the integration of the Internet of Things (IOT) and indoor air quality management
17 into the operation stage. The results are workable guidelines for the automated
18 museum. The tool kit is beneficial as it will save time and cost and increase the
19 efficiency of operation. It will also increase awareness of the necessity of new
20 job opportunities for labor within the technology sector.

21 **Keywords:** Automation, Sustainable Construction, Museum Construction, 3D
22 Printing, Robotics, Internet of Things, Indoor Air Quality.

23 **1 Introduction**

24 The construction sector accounts for approximately half of the total investment of a
25 nation [1]. The prosperity of a nation's economy is therefore directly linked to the
26 prosperity of its construction sector. However, studies indicate that the productivity of
27 the construction industry has recently declined [1]. Hence, in an effort to increase
28 productivity and efficiency, boost sustainability, improve working conditions, and
29 support architectural creativity, automation in construction has become a primary focus
30 of innovators in the industry.

31 Museums are highly particular institutions and hence, normally, have unique
32 designs, structurally and architecturally. Some of the world's most respected
33 constructed facilities are museums. Such examples include the Phaeno Science Center
34 in Germany, New Museum in New York, and the Literature Museum in Marbach. Like
35 any unique construction endeavour, museums require intensive planning. Accordingly,
36 the designers must look at these projects holistically. Cost, environmental impact, time,
37 and indoor air quality are examples of the aspects that require special consideration [2].
38 It follows that the rising need for faster, more efficient, and sustainable construction

39 triggers the interest in automated techniques in the construction of buildings in general,
40 and museums in particular.

41 **1.1 Background**

42 Museums are highly specific structures in terms of the design requirements for their
43 internal environment. This is due to the structures' dual functionality as centers for the
44 preservation of historic artifacts and as educational facilities with a varying influx of
45 visitors. To maintain the function of preservation, internal environmental factors such
46 as humidity, temperature, and pollution must be continuously monitored and controlled
47 [3]. A failure to do so could result in material expansion or shrinkage, mechanical
48 failure, or texture damage in the artifacts [3]. The control of these factors can be
49 achieved efficiently by the use of automation systems such as Building Information
50 Modeling (BIM) during the construction of the structure and the integration of
51 automated heating, ventilation, and air conditioning (HVAC) elements while the
52 structure is in use. Furthermore, museums must ensure the comfort and safety of their
53 visitors. This is easily attainable through the application of process models to control
54 the indoor air quality and through the utilization of BIM in risk management. The
55 requirement for an efficient risk-management system is further accentuated by the
56 historical value of the artifacts. As illustrated in [4], BIM can be used to detect, control,
57 and manage disaster risks by transmitting real-time information on the status of the
58 building and predicting the optimal rescue and control route [4].

59 **1.2 Literature Review**

60 **1.2.1 The need for automation in construction**

61 Makarand Hastak, compares the conventional construction method with the new
62 automated one in his paper: *Advanced automation or conventional construction*
63 *process?* He evaluates whether automation in construction is feasible or not based on
64 five main criteria. These criteria include the following: need-based criteria,
65 technological criteria, economic criteria, project-specific criteria, and safety/risk
66 criteria. Each of these criteria branch into sub-criteria that are also taken into
67 consideration when evaluating the automated model [5].

68 **1.2.2 Feasibility**

69 Turek, et al discuss the interaction between robots and humans. The authors mention
70 the intelligent building (IB) concept, which utilizes mobile robots while also reducing
71 the amount of energy needed in construction. Furthermore, they propose having a
72 bridge between the human-centric view of a building and the robot-centric one. In order
73 to achieve this, three main goals are presented: Mapping, Localization, and Path
74 Planning. This model uses humans' knowledge, along with existing data to recognize
75 the different elements of a building. This is very important when communicating with

76 robots [6]. Further studies discuss the major shift that needs to occur in the construction
77 industry if it were to accommodate automation [7]. They provide points on the
78 incentives for the construction industry to embrace automation and the barriers
79 restricting the entry of robotics to many construction markets.

80 **1.2.3 3D printing**

81 Hager, et al. evaluate the effectiveness and future of 3D building technology. The paper
82 describes the different methods of 3D printing such as stereo-lithography, selective
83 laser sintering (SLS), and Fused Deposition Modeling (FM). The main advantages of
84 3D printing in construction are the reduction of manpower, expenses, construction time,
85 and construction waste and the increase of customization and design flexibility. The
86 main disadvantages are the high cost of the printing materials and the required software
87 packages for the printers, the fact that 3-D printing is an indirect process of
88 construction, the brittleness of a range of the materials and the yet unclear life-cycle
89 performance of the buildings [8]. However, there have been several break-through
90 advances in the field of 3-D printing in construction over the past few years, including
91 the integration of BIM in the process (Wu, Wang, and Wang, 2016).

92 **1.2.4 Building Information Models (BIMs)**

93 Pătrăucean, et al. discuss the as-built building information models or (IB BIMs). As-
94 built BIMs differ than the regular BIMs in the sense that they reflect the actual condition
95 of the building or the project. Moreover, they are essential for when the actual
96 conditions of the building differ from the designed conditions or the as-designed
97 Building Information Models (AD BIM) [10].

98 **1.2.5 Process Models and Robotics**

99 Kasperzyk, et al. present a study of the integration of re-fabrication into a Robotic
100 Prefabrication System (RPS). The authors first explain the benefits of prefabrication
101 in the construction industry, which include cost and time reduction, as well as increased
102 assembly efficiency. However, the use of prefabrication is limited due to the process's
103 inflexibility to design change. Hence, the study presents the concept of "re-fabrication"
104 in RPS, where a prefabricated structure is automatically disassembled and
105 reconstructed according to a design change [11].

106 Škrjanc and Šubic describe the use of an Internal Model Control (IMC) system to
107 control the CO₂ levels of buildings depending on the occupancy fluctuations. The
108 model is simulated in a gallery and the results show a successful achievement of desired
109 air quality coupled with a decrease in operation costs in comparison to the typical air
110 control system. This system is very advantageous in buildings where the occupancy-
111 level fluctuations are high [12].

112 Bock and Linner (2015) suggest five management innovative techniques that are
113 vital in implementing robotics within construction. These are robot-oriented design,

114 robotic industrialization, construction robots, site automation, and ambient robotics
115 [13].

116 **1.2.6 Museum Requirements**

117 Janeen Ault (2000) explains the required environmental factors in museums for the
118 preservation of artifacts and the comfort of visitors. The author states that the main
119 factors requiring consideration are humidity, temperature, light, pollution, and
120 biological attack. Humidity and temperature changes can damage artifacts by causing
121 them to expand or contract. If the artifacts' material is rigidly bound, mechanical failure
122 may occur. Light in the infrared region may also cause severe damage through the
123 dehydration of materials and its effect on their appearance and mechanical strength. Air
124 pollution in the form of sulfur dioxide, oxides of nitrogen or ozone can discolor textiles
125 and fabrics and weaken materials. Finally, biological attacks in the form of fungi and
126 mold consume artifacts and weaken their material. The author tests these environmental
127 factors inside the Field Museum and finds the control severely lacking. She suggests a
128 renovation of the building's HVAC as a solution [3]. This study explains the
129 environmental factors that must be considered in museum construction.

130 **1.3 Statement of the Problem:**

131 In *The future of construction automation: Technological disruption and the upcoming*
132 *ubiquity of robotics*, Thomas Bock (2015) argues that the conventional construction
133 method is slowly reaching its limits, and the need for a new automated one is arising.

134 The project aims to tackle automation specifically in museum construction. The
135 choice of museums as the object of this study is due to the multitude of unique factors
136 associated with these structures. First, the uniqueness of museums invites innovative
137 architectural designs. These new designs include complex details, and hence require
138 prefabrication for vast spans. This can be achieved using an automated system, saving
139 time and easing adaptation to any design change. Secondly, museums have their own
140 environmental specifications. This is because they accommodate large crowds and
141 because they contain objects and collections of high value which must be preserved in
142 a safe, healthy environment.

143 **1.4 Significance of the Project**

144 This project aims to introduce new concepts of automation into the construction and
145 operation of museums. This would simplify and bridge the gap between automation and
146 museum construction. By using museums as an example of a standard and well-defined
147 structure that requires specific construction methods, automation implementation can
148 be applied to other building types ranging from industrial factories and power plants to
149 residential buildings and villa compounds.

150 As the conventional method reaches its limits, many of its fundamental problems
151 such as low worker productivity, high accident rates, deteriorating quality, and shortage
152 of skills [1], can be solved by automating the processes of construction one task at a

153 time. Not only does this technology have the potential of increasing work safety and
 154 comfort, but it can also improve construction efficiency and quality while reducing the
 155 requirement for human intervention in the construction phase. If successfully
 156 implemented, automation tool kits would represent a leap in the industry, increasing
 157 efficiency and project potential.

158 1.5 Objective

159 The objective of this effort is to propose an automation toolkit for museum design,
 160 construction, and operation.

161 2 Automation Toolkit

162 This section presents a toolkit for automation in museum construction and operation. It
 163 is designed to be used when evaluating the level of automation in a particular project.
 164 The rating system that is used follows the Likert scale that ranges from 0 to 5, where 0
 165 represents no level of automation and 5 represents full use of automation. Table (1)
 166 divides automation into two main stages: design and construction, and operation. Each
 167 stage contains multiple automation components. In turn, these components have a
 168 variety of applications, or automation subcomponents, which are also displayed in the
 169 table. Accordingly, each number on the Likert rating scale represents a degree of
 170 automation, or how extensively the automation subcomponents, as listed in table 1, are
 171 used in the museum. 0 indicates there is no automation used in the project, 1 indicates
 172 there is scarce use of automation, 2 means there is a poor use of automation, 3 means
 173 an average amount of automation is used, such that almost half of the project is
 174 automated, 4 shows the project uses a high percentage of automation, while 5 indicates
 175 there is a 100% effective use of automation. In the particular case of robotics, for
 176 example, a 0 rating would mean that there is no use of robotics in any task, a 5 rating
 177 would mean that robotics were used in every possible task they could perform (coating,
 178 painting, finding optimum sequence to design changes, using assembly by disassembly,
 179 and lifting/transporting the equipment) and a 3 rating would mean that robotics were
 180 used in approximately two out of the four tasks they are capable of performing. Table
 181 (2) illustrates the use of the automation toolkit rating scale for a hypothetical museum.
 182 If the hypothetical museum's implementation of automation was evaluated as shown in
 183 the example in table 2, its automation score would average to 3.24, which is considered
 184 an acceptable automation performance.

185 **Table 1.** Automation Toolkit Components

| | <u>Component</u> | <u>Use</u> |
|--|-------------------------------------|--------------------|
| | Building Information Modeling (BIM) | Risk Management |
| | | Budget Maintenance |

| | | |
|----------------------------------|---------------------------|--------------------------------------|
| Design & Construction | | Schedule Maintenance |
| | | Quality Maintenance |
| | | Energy & Carbon footprint Estimation |
| | 3D Printing | Façade component Creation |
| | Robotics | Paint and Coating |
| | | Optimum Design Change Sequence |
| | | Assembly by Disassembly |
| Lift/Transport Equipment | | |
| Operation | Internet of Things (IoT) | HVAC Optimization |
| | | Information |
| | Holographic Display Cases | Object History |
| | | Object Purpose |
| | | Hidden Details |
| | Indoor Air Quality | Carbon Dioxide Monitoring |
| | | Humidity and Temperature Control |

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Table 2. Automation Toolkit Scale Example

| Automated | Likert Scale | | | | | | Description |
|----------------------|--------------|------------|---------|------------|----------|----------|--|
| | 0 | 1 | 2 | 3 | 4 | 5 | |
| | No use | Scarce use | Low use | Acceptable | High use | Full use | |
| Risk Management | | | ✓ | | | | Schedule, cost, and design change tracking |
| Budget Maintenance | | | | ✓ | | | Earned value analysis |
| Schedule Maintenance | | | | | ✓ | | Earned value analysis |

| | | | | | | | |
|--------------------------------------|---|---|---|---|---|---|----------------------------------|
| Quality Maintenance | | ✓ | | | | | BIM quality log |
| Energy & Carbon footprint Estimation | | | ✓ | | | | BIM into Simapro |
| Façade component Creation | ✓ | | | | | | 3D printed designs |
| Paint and Coating | | | | | | ✓ | STCR replacement of manual labor |
| Optimum Design Change Sequence | | | | | | ✓ | Software in re-prefabrication |
| Assembly by Disassembly | | | | | | ✓ | Hardware in re-prefabrication |
| Lift/Transport Equipment | | | | ✓ | | | STCR |
| HVAC Optimization | | | | ✓ | | | Energy saving system |
| Information | | | | | ✓ | | Holographic guides |
| Object History | | | | | ✓ | | Holographic display cases |
| Object Purpose | | | | ✓ | | | Holographic display cases |
| Hidden Details | | | | ✓ | | | Holographic display cases |
| Carbon Dioxide Monitoring | | | | | ✓ | | Air quality control |
| Humidity and Temperature Control | | | | | ✓ | | Air quality control |

187 **3 Discussion**

188 Based on techniques investigated in previous studies, a multitude of automated
 189 construction and operation components are chosen and customized to create an
 190 automation toolkit that best fits the requirements of modern museums.

191 The first step for customizing automated construction and operation methods for
 192 museums is to collect information through research on existing automation methods
 193 and their requirements. Additionally, information about the specific requirements of
 194 museums such as safety, indoor air quality, and visitor comfort and entertainment must
 195 be acquired. The next step is to choose the most suitable automation approaches that
 196 meet museum requirements depending on cost, efficiency, and sustainability. The final
 197 step is to understand how the chosen automation methods complement each other and
 198 how they can be applied together to produce the most efficient and effective model in
 199 construction and operation.

200 4 Conclusions

201 Automation can be applied in the design, construction and operation stages of any
 202 museum. Due to the current limitations within the conventional method, automation
 203 has become an inevitable necessity. It offers various benefits and can save time, energy,
 204 and cost if utilized properly. The presented automation toolkit is designed such that it
 205 can be used to evaluate the level of automation in any project. The components chosen
 206 were based on the optimal level of automation, rather than the maximum one. In other
 207 words, the automation methods were selected according to the optimal levels of cost,
 208 time, and energy. As previously mentioned, labor costs can be reduced up to 40% when
 209 using automation. Automation also minimizes labor transportation thereby saving
 210 energy. The energy recovery wheel within the HVAC system can save energy as well.
 211 Finally, STCRs save time by 37.5%. Time efficiency is also increased due to the use of
 212 IoT and holograms in operation.

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